# National Exams May 2015 04-CHEM-B1, Transport Phenomena <br> 3 hours duration 

## NOTES

1. If doubt exists as to the interpretation of any question, the candidate is urged to submit with the answer paper, a clear statement of any assumptions made.
2. The examination is an OPEN BOOK EXAM.
3. Candidates may use any non-communicating calculator.
4. All problems are worth 25 points. One problem from each of sections A, B, and C must be attempted. A fourth problem from any section must also be attempted.
5. Only the first four questions as they appear in the answer book will be marked.
6. State all assumptions clearly.

## Front Page

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## Section A: Fluid Mechanics

A1. A Newtonian fluid is flowing in laminar flow through a circular horizontal tube of radius R and length $L$. At the entrance the pressure is $p_{0}$ and at the exit the pressure is $p_{L}$. You may assume that gravity forces in this system are negligible, the flow is fully developed and that there is no accumulation in the system. Perform a shell momentum balance and derive an expression for the average velocity of this fluid.

A2. Benzene (density $=0.899 \mathrm{~g} / \mathrm{cm}^{3}$, viscosity $=8 \times 10^{-4} \mathrm{~N} . \mathrm{s} / \mathrm{m}^{2}$ ) flows steadily through a $150-$ meter long horizontal pipe of 5.5 cm inside diameter at a flow rate of 15 liters $/ \mathrm{min}$. The equivalent roughness for the pipe is $8.5 \times 10^{-4} \mathrm{ft}$.
a) [13 points] Calculate the pressure drop.
b) [10 points] What is the pressure drop if the same amount of kerosene (density $=0.82$ $\mathrm{g} / \mathrm{cm}^{3}$, viscosity $=2.5 \times 10^{-3} \mathrm{~N} . \mathrm{s} / \mathrm{m}^{2}$ ) is flowing through the same pipe?
c) [2 points] Explain the difference in pressure drop between (a) and (b).


Moody friction factor (f) vs. Reynolds number (Re) for pipes

## Section B: Heat Transfer

B1. Heat flows through the walls of an annular pipe whose inside and outside radii are $R_{i}$ and $R_{0}$, respectively. The thermal conductivity ( $k$ ) of the material is related to the temperature by the equation $k=a T^{2}+b$, where $a$ and $\square$ are constants.
a) [20 points] Derive the temperature profile of the pipe wall.
b) [5 points] Compute the heat loss through the walls of the pipe.

B2. Nitrobenzene (viscosity $=7 \times 10^{-4} \mathrm{~N} . \mathrm{s} / \mathrm{m}^{2}$, thermal conductivity $=0.15 \mathrm{~W} / \mathrm{m} . \mathrm{K}$, specific heat capacity $=2.38 \mathrm{~J} / \mathrm{g} . \mathrm{K}$ ) at a flow rate of $14,400 \mathrm{~kg} / \mathrm{hr}$ is to be cooled from 400 K to 315 K by heating a stream of benzene from 305 K to 345 K . Two tubular heat exchangers are available each with 44 cm internal diameter shell fitted with 166 tubes. Each tube is 5 m in length with 19 mm outside diameter and 15 mm inside diameter. The tubes are arranged in two passes on 25 mm square pitch with a baffle spacing of 150 mm . There are two passes on the shell side and the operation is to be countercurrent. With benzene passing through the tubes, the anticipated film coefficient on the tube side is $1000 \mathrm{~W} / \mathrm{m}^{2} \mathrm{~K}$. Assuming true cross-flow prevails in the shell and using the figure below for double shell pass exchangers, what value of scale resistance could be allowed if these heat exchangers were used?


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## Section C: Mass Transfer

C1. The convection mass transfer coefficient $\mathrm{k}_{\mathrm{c}}$ is useful for determining the rate convection from a surface where the concentration is constant into the flowing medium. It relates the local flux to the concentration difference given by $N_{A}=k_{c}\left(C_{A s}-C_{A 0}\right)$, where $C_{A s}$ is the surface concentration and $\mathrm{C}_{\mathrm{A} 0}$ is the far-field or baseline/background concentration.

For laminar flow across a flat plate, the Sherwood number (Sh) is given by the equation

$$
\mathrm{Sh}=\mathrm{k}_{\mathrm{c}} \mathrm{x} / \mathrm{D}_{\mathrm{AB}}=0.332\left(\operatorname{Re}_{\mathrm{x}}\right)^{1 / 2}(\mathrm{Sc})^{1 / 3}
$$

where Schmidt number $(S c)=v / D_{A B}$, Reynold's number $\left(\operatorname{Re}_{x}\right)=v_{\max } x / v$, and kinematic viscosity $(v)=\mu / \rho$.

Water is flowing through a pipe of radius R at flow rate of Q . One small section of the pipe of length $L$ is made of lead. The solubility of lead salts in water (containing oxygen) at system temperature is $\mathrm{S}(\mu \mathrm{M})$. As you know, lead is toxic and thus, the concentration needs to be minimized. Assume the diffusion boundary layer is much smaller than R, and that flow is laminar throughout. Also assume that the inlet water is free of lead salts.
a) [7 points] Derive an expression for the flux as a function of length along the pipe.
b) [ 5 points] Derive an expression for the total amount of lead entering the water per unit time.
c) [5 points] Derive an expression for the average lead concentration at the outlet of the pipe.
d) [ 8 points] How much would the concentration of lead change at the outlet when the temperature is increased from $25^{\circ} \mathrm{C}$ to $100^{\circ} \mathrm{C}$ ? The viscosity of water at $25^{\circ} \mathrm{C}$ and 100 ${ }^{\circ} \mathrm{C}$ is $9 \times 10^{-4}$ Pa.s and $2.7 \times 10^{-4} \mathrm{~Pa} . \mathrm{s}$, respectively. The solubility of lead salts in water containing oxygen at $100^{\circ} \mathrm{C}$ is twice that at $25^{\circ} \mathrm{C}$.

C2. A swimming pool is $80 \%$ full. In the time interval $t_{1}, 10 \%$ of the water evaporates, dropping the water level from $80 \%$ to $70 \%$ full. In the time interval $t_{2}$, another $10 \%$ of water evaporates, dropping its water level from $70 \%$ to $60 \%$. Assume the gentle breeze above the pool is constant over time.
a) [ 3 points] Write the assumptions necessary to calculate the time two intervals, $t_{1}$ and $t_{2}$.
b) [11 points] Write the expression for average evaporating flux $\mathrm{N}_{\mathrm{A}}$.
c) [11 points] Obtain an expression each for time intervals $t_{1}$ and $t_{2}$, and calculate the ratio $\mathrm{t}_{2} / \mathrm{t}_{1}$.

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## APPENDIX A

## Summary of the Conservation Equations

Table A. 1 The Continuity Equation

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}+(\nabla \cdot \rho \vec{u})=0 \tag{1.1}
\end{equation*}
$$

Rectangular coordinates $(x, y, z)$

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}+\frac{\partial}{\partial x}\left(\rho u_{x}\right)+\frac{\partial}{\partial y}\left(\rho u_{y}\right)+\frac{\partial}{\partial z}\left(\rho u_{z}\right)=0 \tag{1.1a}
\end{equation*}
$$

Cylindrical coordinates ( $r, \theta, z$ )

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}+\frac{1}{r} \frac{\partial}{\partial r}\left(\rho r u_{r}\right)+\frac{1}{r} \frac{\partial}{\partial \theta}\left(\rho u_{\theta}\right)+\frac{\partial}{\partial z}\left(\rho u_{z}\right)=0 \tag{1.1b}
\end{equation*}
$$

Spherical coordinates ( $r, \theta, \phi$ )

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}+\frac{1}{r^{2}} \frac{\partial}{\partial r}\left(\rho r^{2} u_{r}\right)+\frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}\left(\rho u_{\theta} \sin \theta\right)+\frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}\left(\rho u_{\phi}\right)=0 \tag{1.1c}
\end{equation*}
$$

Table A. 2 The Navier-Stokes equations for Newtonian fluids of constant $\rho$ and $\mu$

$$
\begin{equation*}
\frac{\partial \vec{u}}{\partial t}+(\vec{u} \cdot \nabla) \vec{u}=-\frac{1}{\rho} \nabla P+\vec{g}+v\left(\nabla^{2} \vec{u}\right) \tag{A2}
\end{equation*}
$$

Rectangular coordinates $(x, y, z)$
$x$-component $\quad \frac{\partial u_{x}}{\partial t}+u_{x} \frac{\partial u_{x}}{\partial x}+u_{y} \frac{\partial u_{x}}{\partial y}+u_{z} \frac{\partial u_{x}}{\partial z}=-\frac{1}{\rho} \frac{\partial P}{\partial x}+g_{x}+v\left(\frac{\partial^{2} u_{x}}{\partial x^{2}}+\frac{\partial^{2} u_{x}}{\partial y^{2}}+\frac{\partial^{2} u_{x}}{\partial z^{2}}\right)$
$y$-component $\quad \frac{\partial u_{y}}{\partial t}+u_{x} \frac{\partial u_{y}}{\partial x}+u_{y} \frac{\partial u_{y}}{\partial y}+u_{z} \frac{\partial u_{y}}{\partial z}=-\frac{1}{\rho} \frac{\partial P}{\partial y}+g_{y}+v\left(\frac{\partial^{2} u_{y}}{\partial x^{2}}+\frac{\partial^{2} u_{y}}{\partial y^{2}}+\frac{\partial^{2} u_{y}}{\partial z^{2}}\right)$
$z$-component $\quad \frac{\partial u_{z}}{\partial t}+u_{x} \frac{\partial u_{z}}{\partial x}+u_{y} \frac{\partial u_{z}}{\partial y}+u_{z} \frac{\partial u_{z}}{\partial z}=-\frac{1}{\rho} \frac{\partial P}{\partial z}+g_{z}+v\left(\frac{\partial^{2} u_{z}}{\partial x^{2}}+\frac{\partial^{2} u_{z}}{\partial y^{2}}+\frac{\partial^{2} u_{z}}{\partial z^{2}}\right)$

Cylindrical coordinates ( $r, \theta, z$ )

$$
\frac{\partial u_{r}}{\partial t}+u_{r} \frac{\partial u_{r}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial u_{r}}{\partial \theta}+u_{z} \frac{\partial u_{r}}{\partial z}-\frac{u_{\theta}^{2}}{r}
$$

$r$-component

$$
\begin{align*}
& =-\frac{1}{\rho} \frac{\partial P}{\partial r}+g_{r}+v\left[\frac{\partial}{\partial r}\left(\frac{1}{r} \frac{\partial\left(r u_{r}\right)}{\partial r}\right)+\frac{1}{r^{2}} \frac{\partial^{2} u_{r}}{\partial \theta^{2}}-\frac{2}{r^{2}} \frac{\partial u_{\theta}}{\partial \theta}+\frac{\partial^{2} u_{r}}{\partial z^{2}}\right]  \tag{A2d}\\
& \frac{\partial u_{\theta}}{\partial t}+u_{r} \frac{\partial u_{\theta}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial u_{\theta}}{\partial \theta}+u_{z} \frac{\partial u_{\theta}}{\partial z}+\frac{u_{r} u_{\theta}}{r}
\end{align*}
$$

$\theta$-component

$$
\begin{equation*}
=-\frac{1}{\rho r} \frac{\partial P}{\partial \theta}+g_{\theta}+v\left[\frac{\partial}{\partial r}\left(\frac{1}{r} \frac{\partial\left(r u_{\theta}\right)}{\partial r}\right)+\frac{1}{r^{2}} \frac{\partial^{2} u_{\theta}}{\partial \theta^{2}}+\frac{2}{r^{2}} \frac{\partial u_{r}}{\partial \theta}+\frac{\partial^{2} u_{\theta}}{\partial z^{2}}\right] \tag{A2e}
\end{equation*}
$$

$$
\frac{\partial u_{z}}{\partial t}+u_{r} \frac{\partial u_{z}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial u_{z}}{\partial \theta}+u_{z} \frac{\partial u_{z}}{\partial z}
$$

$z$-component

$$
\begin{equation*}
=-\frac{1}{\rho} \frac{\partial P}{\partial z}+g_{z}+v\left[\frac{1}{r} \frac{\partial}{\partial r}\left(r \frac{\partial u_{z}}{\partial r}\right)+\frac{1}{r^{2}} \frac{\partial^{2} u_{z}}{\partial \theta^{2}}+\frac{\partial^{2} u_{z}}{\partial z^{2}}\right] \tag{A2f}
\end{equation*}
$$

Spherical coordinates ( $r, \theta, \phi$ )

$$
\frac{\partial u_{r}}{\partial t}+u_{r} \frac{\partial u_{r}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial u_{r}}{\partial \theta}+\left(\frac{u_{\phi}}{r \sin \theta}\right) \frac{\partial u_{r}}{\partial \phi}-\frac{u_{\theta}^{2}}{r}-\frac{u_{\phi}^{2}}{r}=-\frac{1}{\rho} \frac{\partial P}{\partial r}+g_{r}
$$

$r$-component

$$
\begin{equation*}
+v\left[\frac{1}{r^{2}} \frac{\partial^{2}}{\partial r^{2}}\left(r^{2} u_{r}\right)+\frac{1}{r^{2} \sin \theta} \frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial u_{r}}{\partial \theta}\right)+\frac{1}{r^{2} \sin ^{2} \theta} \frac{\partial^{2} u_{r}}{\partial \phi^{2}}\right] \tag{A2g}
\end{equation*}
$$

$$
\frac{\partial u_{\theta}}{\partial t}+u_{r} \frac{\partial u_{\theta}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial u_{\theta}}{\partial \theta}+\left(\frac{u_{\phi}}{r \sin \theta}\right) \frac{\partial u_{\theta}}{\partial \phi}+\frac{u_{r} u_{\theta}}{r}-\frac{u_{\phi}^{2}}{r} \cot \theta=-\frac{1}{\rho r} \frac{\partial P}{\partial \theta}+g_{\theta}
$$

Q-component

$$
\begin{align*}
& +v\left[\begin{array}{l}
\frac{1}{r^{2}} \frac{\partial}{\partial r}\left(r^{2} \frac{\partial u_{\theta}}{\partial r}\right)+\frac{1}{r^{2}} \frac{\partial}{\partial \theta}\left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta}\left(u_{\theta} \sin \theta\right)\right)+\frac{1}{r^{2} \sin ^{2} \theta} \frac{\partial^{2} u_{\theta}}{\partial \phi^{2}} \\
+\frac{2}{r^{2}} \frac{\partial u_{r}}{\partial \theta}-\frac{2 \cot \theta}{r^{2} \sin \theta} \frac{\partial u_{\phi}}{\partial \phi}
\end{array}\right]  \tag{A2h}\\
& \frac{\partial u_{\phi}}{\partial t}+u_{r} \frac{\partial u_{\phi}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial u_{\phi}}{\partial \theta}+\frac{u_{\phi}}{r \sin \theta} \frac{\partial u_{\phi}}{\partial \phi}+\frac{u_{r} u_{\phi}}{r}+\frac{u_{\theta} u_{\phi}}{r} \cot \theta=-\frac{1}{\rho r \sin \theta} \frac{\partial P}{\partial \phi}
\end{align*}
$$

$\phi$-component

$$
+g_{\varphi}+v\left[\begin{array}{l}
\frac{1}{r^{2}} \frac{\partial}{\partial r}\left(r^{2} \frac{\partial u_{\phi}}{\partial r}\right)+\frac{1}{r^{2}} \frac{\partial}{\partial \theta}\left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta}\left(u_{\phi} \sin \theta\right)\right)+\frac{1}{r^{2} \sin ^{2} \theta} \frac{\partial^{2} u_{\phi}}{\partial \phi^{2}}  \tag{A2i}\\
+\frac{2}{r^{2} \sin \theta} \frac{\partial u_{r}}{\partial \phi}+\frac{2 \cot \theta}{r^{2} \sin \theta} \frac{\partial u_{\theta}}{\partial \phi}
\end{array}\right]
$$

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Table A. 3 The Energy Equation for Incompressible Media

$$
\begin{equation*}
\rho c_{P}\left[\frac{\partial T}{\partial t}+(\vec{u} \cdot \nabla)(T)\right]=[\nabla \cdot k \nabla T]+\dot{T}_{G} \tag{A3}
\end{equation*}
$$

Rectangular coordinates $(x, y, z)$

$$
\begin{equation*}
\rho c_{P}\left[\frac{\partial T}{\partial t}+u_{x} \frac{\partial T}{\partial x}+u_{y} \frac{\partial T}{\partial y}+u_{z} \frac{\partial T}{\partial z}\right]=\frac{\partial}{\partial x}\left(k \frac{\partial T}{\partial x}\right)+\frac{\partial}{\partial y}\left(k \frac{\partial T}{\partial y}\right)+\frac{\partial}{\partial z}\left(k \frac{\partial T}{\partial z}\right)+\dot{T}_{G} \tag{A3a}
\end{equation*}
$$

Cylindrical coordinates ( $r, \theta, z$ )

$$
\begin{equation*}
\rho c_{P}\left[\frac{\partial T}{\partial t}+u_{r} \frac{\partial T}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial T}{\partial \theta}+u_{z} \frac{\partial T}{\partial z}\right]=\frac{1}{r} \frac{\partial}{\partial r}\left(r k \frac{\partial T}{\partial r}\right)+\frac{1}{r^{2}} \frac{\partial}{\partial \theta}\left(k \frac{\partial T}{\partial \theta}\right)+\frac{\partial}{\partial z}\left(k \frac{\partial T}{\partial z}\right)+\dot{T}_{G} \tag{A3b}
\end{equation*}
$$

Spherical coordinates ( $r, \theta, \phi$ )

$$
\begin{align*}
& \rho c_{P}\left[\frac{\partial T}{\partial t}+u_{r} \frac{\partial T}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial T}{\partial \theta}+\frac{u_{\phi}}{r \sin \theta} \frac{\partial T}{\partial \phi}\right]= \\
& \frac{1}{r^{2}} \frac{\partial}{\partial r}\left(r^{2} k \frac{\partial T}{\partial r}\right)+\frac{1}{r^{2} \sin \theta} \frac{\partial}{\partial \theta}\left(k \sin \theta \frac{\partial T}{\partial \theta}\right)+\frac{1}{r^{2} \sin ^{2} \theta} \frac{\partial}{\partial \phi}\left(k \frac{\partial T}{\partial \phi}\right)+\dot{T}_{G} \tag{A3c}
\end{align*}
$$

Table A4: The continuity equation for species $A$ in terms of the molar flux

$$
\begin{equation*}
\frac{\partial C_{A}}{\partial t}=-\left(\nabla \cdot \vec{N}_{A}\right)+\dot{R}_{A, G} \tag{4.}
\end{equation*}
$$

Rectangular coordinates $(x, y, z)$

$$
\begin{equation*}
\frac{\partial C_{A}}{\partial t}=-\left(\frac{\partial\left[N_{A}\right]_{z}}{\partial x}+\frac{\partial\left[N_{A}\right]_{y}}{\partial y}+\frac{\partial\left[N_{A}\right]_{z}}{\partial z}\right)+\dot{R}_{A, G} \tag{4a}
\end{equation*}
$$

Cylindrical coordinates $(r, \theta, z)$

$$
\begin{equation*}
\frac{\partial C_{A}}{\partial t}=-\left\{\frac{1}{r} \frac{\partial}{\partial r}\left[r N_{A}\right]_{r}+\frac{1}{r} \frac{\partial}{\partial \theta}\left[N_{A}\right]_{\theta}+\frac{\partial}{\partial z}\left[N_{A}\right]_{z}\right\}+\dot{R}_{A, G} \tag{4b}
\end{equation*}
$$

Spherical coordinates $(r, \theta, \phi)$

$$
\begin{equation*}
\frac{\partial C_{A}}{\partial t}=-\left\{\frac{1}{r^{2}} \frac{\partial}{\partial r}\left(r^{2}\left[N_{A}\right]_{r}\right)+\frac{1}{r \sin \theta} \frac{\partial}{\partial \theta}\left(\left[N_{A}\right]_{\theta} \sin \theta\right)+\frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}\left[N_{A}\right]_{\phi}\right\}+\dot{R}_{A, G} \tag{4c}
\end{equation*}
$$

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Table A.5: The continuity equation for species $A$

$$
\begin{equation*}
\frac{\partial C_{A}}{\partial t}+(\vec{u} \cdot \nabla) C_{A}=D_{A} \nabla^{2} C_{A}+\dot{R}_{A, G} \tag{5}
\end{equation*}
$$

Rectangular coordinates $(x, y, z)$

$$
\begin{equation*}
\frac{\partial C_{A}}{\partial t}+u_{x} \frac{\partial C_{A}}{\partial x}+u_{y} \frac{\partial C_{A}}{\partial y}+u_{z} \frac{\partial C_{A}}{\partial z}=\frac{\partial}{\partial x}\left(D \frac{\partial C_{A}}{\partial x}\right)+\frac{\partial}{\partial y}\left(D \frac{\partial C_{A}}{\partial y}\right)+\frac{\partial}{\partial z}\left(D \frac{\partial C_{A}}{\partial z}\right)+\dot{R}_{A, G} \tag{5a}
\end{equation*}
$$

Cylindrical coordinates ( $r, \theta, z$ )

$$
\begin{equation*}
\frac{\partial C_{A}}{\partial t}+u_{r} \frac{\partial C_{A}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial C_{A}}{\partial \theta}+u_{z} \frac{\partial C_{A}}{\partial z}=\frac{1}{r} \frac{\partial}{\partial r}\left(r D \frac{\partial C_{A}}{\partial r}\right)+\frac{1}{r^{2}} \frac{\partial}{\partial \theta}\left(D \frac{\partial C_{A}}{\partial \theta}\right)+\frac{\partial}{\partial z}\left(D \frac{\partial C_{A}}{\partial z}\right)+\dot{R}_{A, G} \tag{5b}
\end{equation*}
$$

Spherical coordinates $(r, \theta, \phi)$

$$
\begin{align*}
& \frac{\partial C_{A}}{\partial t}+u_{r} \frac{\partial C_{A}}{\partial r}+\frac{u_{\theta}}{r} \frac{\partial C_{A}}{\partial \theta}+\frac{u_{\phi}}{r \sin \theta} \frac{\partial C_{A}}{\partial \phi}=\frac{1}{r^{2}} \frac{\partial}{\partial r}\left(r^{2} D \frac{\partial C_{A}}{\partial r}\right) \\
& +\frac{1}{r^{2} \sin \theta} \frac{\partial}{\partial \theta}\left(D \sin \theta \frac{\partial C_{A}}{\partial \theta}\right)+\frac{1}{r^{2} \sin ^{2} \theta} \frac{\partial}{\partial \phi}\left(D \frac{\partial C_{A}}{\partial \phi}\right)+\dot{R}_{A, G} \tag{5c}
\end{align*}
$$

