

**National December 2018**

**16-Mec-A3, SYSTEM ANALYSIS AND CONTROL**

3 hours duration

**Notes:**

1. If doubt exists as to the interpretation of any question, the candidate is urged to submit with the answer paper, a clear statement of any assumptions made.
2. Candidates may use a Casio or Sharp approved calculator. This is a **closed book** exam. No aids other than semi-log graph papers are permitted.
3. Any four (4) questions constitute a complete paper. Only the first four (4) questions as they appear in your answer book will be marked.
4. All questions are of equal value.

**Question 1:**

Consider the second-order system with the transfer function,

$$G(s) = \frac{3}{(s^2 + 2s - 3)}$$

- a) Determine the DC gain for this system.
- b) What is the final value of the step response of this system?

**Question 2:**

A typical transfer function for a tape-drive system would be (with time in milliseconds),

$$G(s) = \frac{k(s+4)}{s[(s+0.5)(s+1)(s^2+0.4s+4)]}$$

From Routh's criterion, what is the range of  $k$  for which this system is stable if the characteristic equation is  $1+G(s) = 0$  ?

**Question 3:**

A unity feedback system has the plant transfer function

$$kG(s) = \frac{k}{s(s^2 + 6s + 12)}$$

We wish to investigate the root locus versus  $k$ .

- Plot the location of poles and zeros of  $G(s)$  showing segments of the root locus on the real axis,
- What are the departure angles from the complex poles?
- Where are the breakaway and break-in points?
- Sketch the root locus,
- What is the value of  $k$  at the point where the closed-loop complex roots have damping ratio  $\zeta = 0.5$ ?

**Question 4:**

For the unity feedback system with

$$G(s) = \frac{1}{s(s+1)\left[\left(\frac{s^2}{25}\right) + 0.4\left(\frac{s}{5}\right) + 1\right]}$$

- Draw the Bode plots (gain and phase) for  $G(j\omega)$ .
- Indicate the gain margin when the gain is set for a phase margin of  $45^\circ$ .

**Question 5:**

- Using the Laplace transform technique, find the transient and steady-state responses of the system described by the differential equation

$$\frac{d^2 y}{dt^2} + 3\frac{dy}{dt} + 2y = 1$$

With initial conditions

$$y(0^+) \text{ and } \left. \frac{dy}{dt} \right|_{t=0^+} = 1$$

- b) Using the LaPlace transform technique, find the unit impulse response of the system described by the differential equation

$$\frac{d^3 y}{dt^3} + \frac{dy}{dt} = x$$

**Question 6:**

- a) What is the step response of a system whose transfer function has a zero at -1, a pole at -2, and a gain factor of 2?
- b) Determine the time response  $y(t)$  for the following transformed equation:

$$Y(S) = \frac{s+4}{s(s+1)(s+2)}$$

**Question 7:**

Determine the position, velocity and acceleration error constants and then determine the steady-state error to a unit step, a unit ramp, and a unit parabolic input for the system shown below.

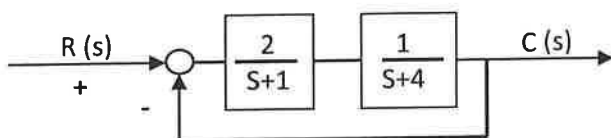


Table of Laplace Transforms

$f(t)$	$\mathcal{L}[f(t)] = F(s)$		$f(t)$	$\mathcal{L}[f(t)] = F(s)$	
1	$\frac{1}{s}$	(1)	$\frac{ae^{at} - be^{bt}}{a - b}$	$\frac{s}{(s - a)(s - b)}$	(19)
$e^{at} f(t)$	$F(s - a)$	(2)	$t e^{at}$	$\frac{1}{(s - a)^2}$	(20)
$\mathcal{U}(t - a)$	$\frac{e^{-as}}{s}$	(3)	$t^n e^{at}$	$\frac{n!}{(s - a)^{n+1}}$	(21)
$f(t - a)\mathcal{U}(t - a)$	$e^{-as}F(s)$	(4)	$e^{at} \sin kt$	$\frac{k}{(s - a)^2 + k^2}$	(22)
$\delta(t)$	1	(5)	$e^{at} \cos kt$	$\frac{s - a}{(s - a)^2 + k^2}$	(23)
$\delta(t - t_0)$	$e^{-st_0}$	(6)	$e^{at} \sinh kt$	$\frac{k}{(s - a)^2 - k^2}$	(24)
$t^n f(t)$	$(-1)^n \frac{d^n F(s)}{ds^n}$	(7)	$e^{at} \cosh kt$	$\frac{s - a}{(s - a)^2 - k^2}$	(25)
$f'(t)$	$sF(s) - f(0)$	(8)	$t \sin kt$	$\frac{2ks}{(s^2 + k^2)^2}$	(26)
$f^n(t)$	$s^n F(s) - s^{n-1}f(0) - \dots - f^{(n-1)}(0)$	(9)	$t \cos kt$	$\frac{s^2 - k^2}{(s^2 + k^2)^2}$	(27)
$\int_0^t f(x)g(t-x)dx$	$F(s)G(s)$	(10)	$t \sinh kt$	$\frac{2ks}{(s^2 - k^2)^2}$	(28)
$t^n$ ( $n = 0, 1, 2, \dots$ )	$\frac{n!}{s^{n+1}}$	(11)	$t \cosh kt$	$\frac{s^2 - k^2}{(s^2 - k^2)^2}$	(29)
$t^x$ ( $x \geq -1 \in \mathbb{R}$ )	$\frac{\Gamma(x + 1)}{s^{x+1}}$	(12)	$\frac{\sin at}{t}$	$\arctan \frac{a}{s}$	(30)
$\sin kt$	$\frac{k}{s^2 + k^2}$	(13)	$\frac{1}{\sqrt{\pi t}} e^{-a^2/4t}$	$\frac{e^{-a\sqrt{s}}}{\sqrt{s}}$	(31)
$\cos kt$	$\frac{s}{s^2 + k^2}$	(14)	$\frac{a}{2\sqrt{\pi t^3}} e^{-a^2/4t}$	$e^{-a\sqrt{s}}$	(32)
$e^{at}$	$\frac{1}{s - a}$	(15)	$\operatorname{erfc}\left(\frac{a}{2\sqrt{t}}\right)$	$\frac{e^{-a\sqrt{s}}}{s}$	(33)
$\sinh kt$	$\frac{k}{s^2 - k^2}$	(16)			
$\cosh kt$	$\frac{s}{s^2 - k^2}$	(17)			
$\frac{e^{at} - e^{bt}}{a - b}$	$\frac{1}{(s - a)(s - b)}$	(18)			